GLOBAL OPTIMIZATION

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Other Global Optimization:

- Constant Propagation
- Dead-code elimination
- Liveness analysis
- Common subexpression elimination
- Loop optimization

Local Optimization

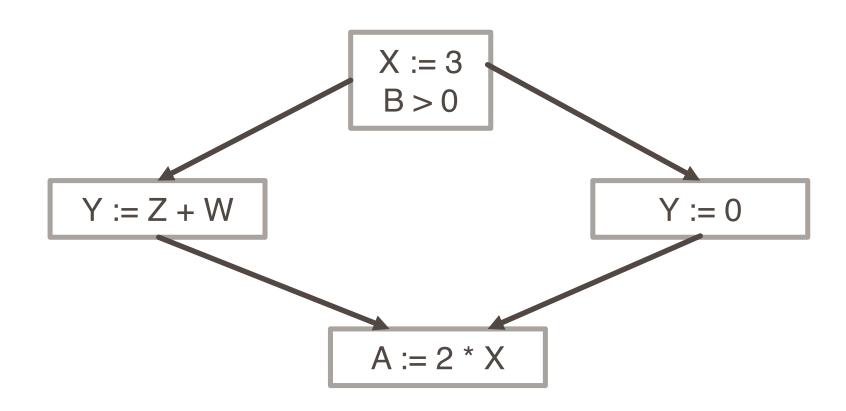
- Recall the simple basic-block optimizations
 - Constant propagation
 - Dead code elimination

$$X := 3$$

 $Y := Z * W$
 $Q := X + Y$
 $X := 3$
 $Y := Z * W$
 $Q := 3 + Y$

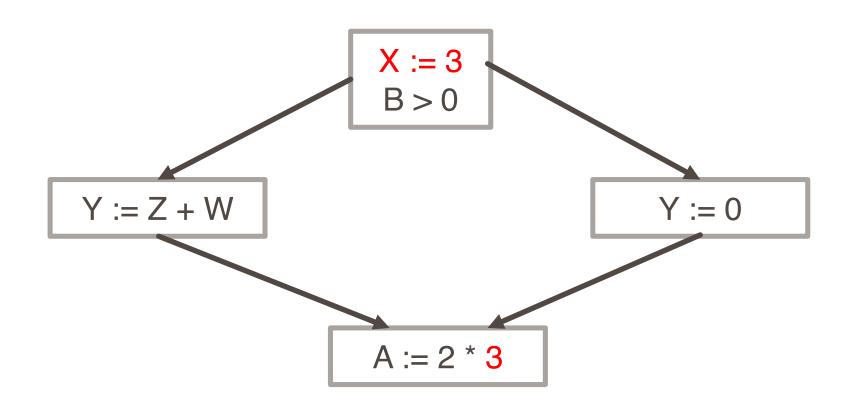
Global Optimization

These optimizations can be extended to an entire control-flow graph



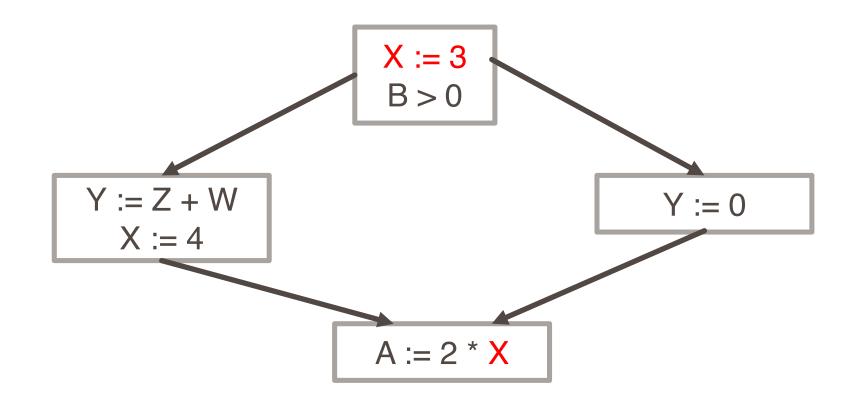
Global Optimization

These optimizations can be extended to an entire control-flow graph



Correctness

- How do we know it is OK to globally propagate constants?
- There are situations where it is incorrect:



Correctness (cont..)

To replace a use of x by a constant k we must know that:

On every path to the use of x, the last assignment to x is

$$x := k$$

- The correctness condition is not trivial to check
- "All paths" includes paths around loops and through branches of conditionals
- Checking the condition requires global analysis
 - An analysis of the entire control-flow graph

Global Analysis

- Global optimization tasks share several traits:
 - The optimization depends on knowing a property X at a particular point in program execution
 - Proving X at any point requires knowledge of the entire program
 - It is OK to be conservative. If the optimization requires X to be true, then want to know either
 - X is definitely true
 - Don't know if X is true
 - It is always safe to say "don't know"

Global Analysis (cont..)

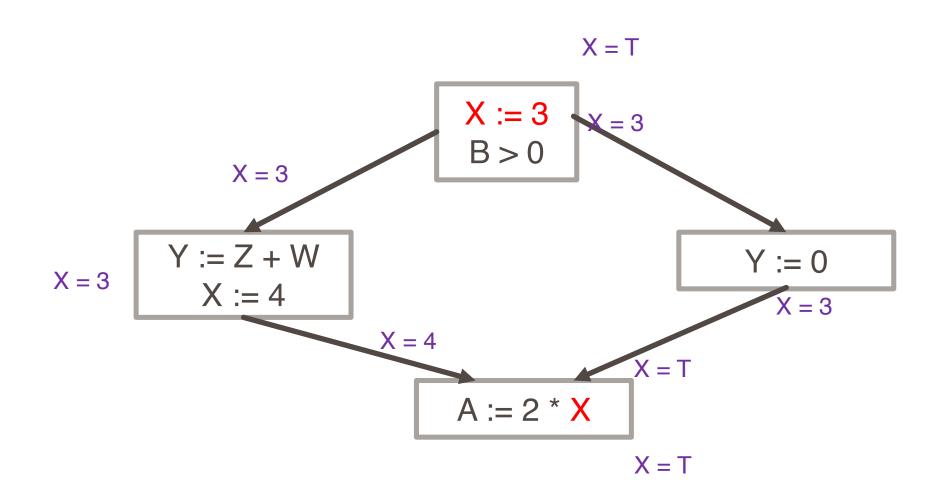
- Global dataflow analysis is a standard technique for solving problems with these characteristics
- Global constant propagation is one example of an optimization that requires global dataflow analysis

Global Constant Propagation (Cont.)

 To make the problem precise, we associate one of the following values with X at every program point

value	interpretation
⊥ ("bottom")	This statement never executes
C	X = constant c
T ("top")	X is not a constant

Example



Using the Information

- Given global constant information, it is easy to perform the optimization
 - Simply inspect the x = ? associated with a statement using x
 - If x is constant at that point replace that use of x by the constant
- But how do we compute the properties x = ?

Using the Information

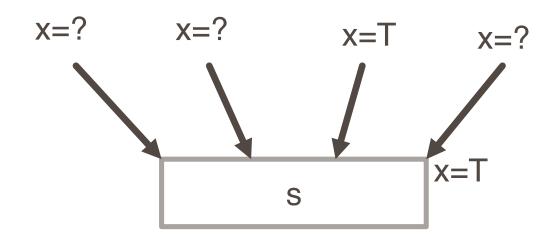
- The idea is to "push" or "transfer" information from one statement to the next
- For each statement s, we compute information about the value of x immediately before and after s

```
C(s,x,in) = value of x before s

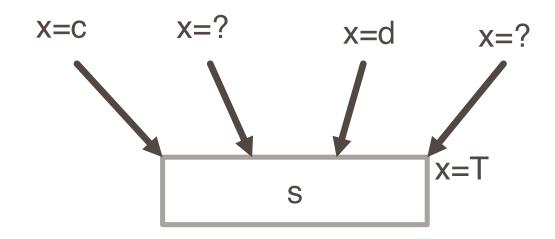
C(s,x,out) = value of x after s
```

Transfer Functions

- Define a transfer function that transfers information one statement to another
- In the following rules, let statement s have immediate predecessor statements p₁,...,p_n

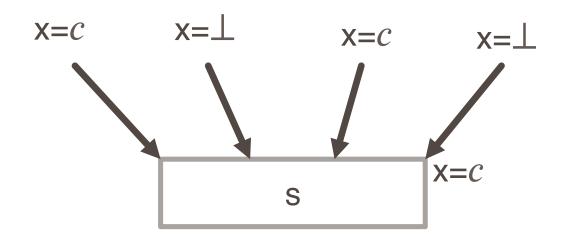


if $C(p_i, x, out) = T$ for any i, then C(s, x, in) = T

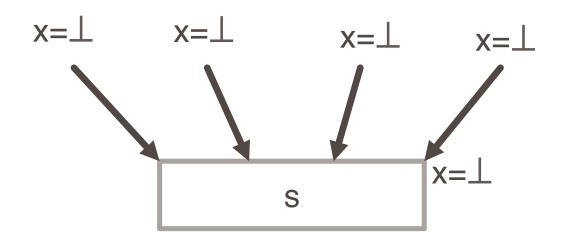


$$C(p_i, x, out) = c \& C(p_j, x, out) = d \& d \Leftrightarrow c$$

then $C(s, x, in) = T$

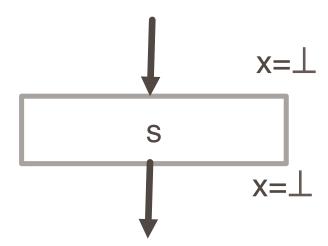


if $C(p_i, x, out) = c$ or \bot for all i, then C(s, x, in) = c



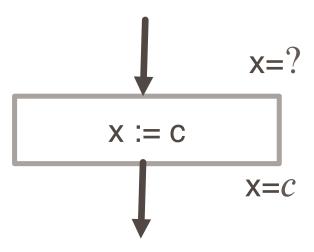
if
$$C(p_i, x, out) = \bot$$
 for all i,
then $C(s, x, in) = \bot$

- Rules 1-4 relate the out of one statement to the in of the next statement
- Now we need rules relating the in of a statement to the out of the same statement

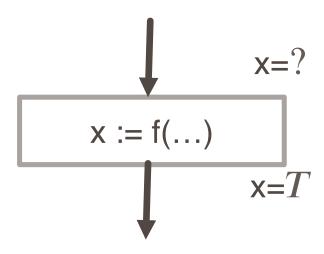


$$C(s, x, out) = \bot$$

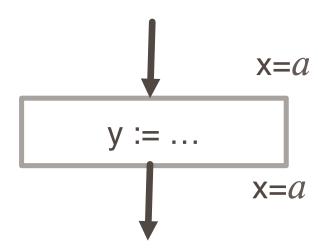
if $C(s, x, in) = \bot$



C(x := c, x, out) = c if c is a constant



$$C(x := f(...), x, out) = T$$



C(y := ..., x, out) = C(y := ..., x, in) if x >> y

Algorithm

- 1. For every entry s to the program, set C(s, x, in) = T
- 2. Set C(s, x, in) = C(s, x, out) = \perp everywhere else
- 3. Repeat until all points satisfy 1-8:
 - Pick s not satisfying 1-8 and update using the appropriate rule

Ordering:

• We can simplify the presentation of the analysis by ordering the values $\bot < c < T$

Common subexpression elimination

• Example:

$$a := b + c$$
 $a := b + c$
 $c := b + c$ \Rightarrow $c := a$
 $d := b + c$ $d := b + c$

- Example in array index calculations
 - c[i+1] := a[i+1] + b[i+1]
 - During address computation, i+1 should be reused
 - Not visible in high level code, but in intermediate code

Code Elimination

Unreachable code elimination

- Construct the control flow graph
- Unreachable code block will not have an incoming edge
- After constant propagation/folding, unreachable branches can be eliminated

Dead code elimination

Ineffective statements

```
    x := y + 1 (immediately redefined, eliminate!)
    y := 5 ⇒ y := 5
    x := 2 * z
    x := 2 * z
```

- A variable is dead if it is never used after last definition
 - Eliminate assignments to dead variables
- Need to do data flow analysis to find dead variables

Function Optimization

Function inlining

- Replace a function call with the body of the function
- Save a lot of copying of the parameters, return address, etc.

Function cloning

Create specialized code for a function for different calling parameters

Loop optimization

- Consumes 90% of the execution time
 - ⇒ a larger payoff to optimize the code within a loop

Techniques

- Loop invariant detection and code motion
- Induction variable elimination
- Strength reduction in loops
- Loop unrolling
- Loop peeling
- Loop fusion

Loop invariant detection

- If the result of a statement or expression does not change within a loop, and it has no external side-effect
- Computation can be moved to outside of the loop
- Example

```
for (i=0; i<n; i++) a[i] := a[i] + x/y;
```

Three address code

```
for (i=0; i<n; i++) { c := x/y; a[i] := a[i] + c; } 
 \Rightarrow c := x/y; 
 for (i=0; i<n; i++) a[i] := a[i] + c;
```

Code Motion

- Reduce frequency with which computation performed
 - If it will always produce same result
 - Especially moving code out of loop

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    a[n*i + j] = b[j];

for (i = 0; i < n; i++) {
    int ni = n*i;
    for (j = 0; j < n; j++)
        a[ni + j] = b[j];
}</pre>
```

- Strength reduction in loops
 - Replace costly operation with simpler one
 - Shift, add instead of multiply or divide

$$16*x --> x << 4$$

- Depends on cost of multiply or divide instruction
- Recognize sequence of products

```
for (i = 0; i < n; i++)
for (j = 0; j < n; j++)
a[n*i + j] = b[j];
```

```
int ni = 0;
for (i = 0; i < n; i++) {
  for (j = 0; j < n; j++)
    a[ni + j] = b[j];
  ni += n;
}</pre>
```

- Strength reduction in loops
 - Replace costly operation with simpler one
 - Shift, add instead of multiply or divide

```
16*x --> x << 4
```

- Depends on cost of multiply or divide instruction
- Recognize sequence of products

```
s := 0;
for (i=0; i<n; i++)
{
    v := 4 * i;
    s := s + v;
}</pre>
s := 0;
for (i=0; i<n; i++)
    {
    v := v + 4;
    s := s + v;
}</pre>
```

- Induction variable elimination
 - If there are multiple induction variables in a loop, can eliminate the ones which are used only in the test condition
 - Example

```
s := 0; for (i=0; i<n; i++) { s := 4 * i; ... } -- i is not referenced in loop \Rightarrow s := 0; e := 4*n; while (s < e) { s := s + 4; }
```

```
s := 0;
for (i=0; i<n; i++)
{ s := 4 * i; ... }
-- i is not referenced in loop</pre>
s := 0;
e := 4*n;
while (s < e) {
s := s + 4;
}
```

Code Optimization Techniques

Loop unrolling

- Execute loop body multiple times at each iteration
- Get rid of the conditional branches, if possible
- Allow optimization to cross multiple iterations of the loop
 - Especially for parallel instruction execution
- Space time tradeoff
 - Increase in code size, reduce some instructions

Loop peeling

- Similar to unrolling
- But unroll the first and/or last few iterations

Loop fusion

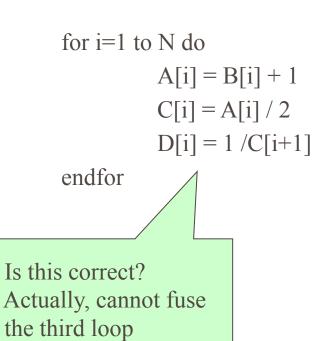
```
Example
for i=1 to N do
A[i] = B[i] + 1
endfor
for i=1 to N do
C[i] = A[i] / 2
endfor
for i=1 to N do
D[i] = 1 / C[i+1]
endfor
```

```
for i=1 to N do A[i] = B[i] + 1 C[i] = A[i] / 2 D[i] = 1 / C[i+1] endfor
```

Before Loop Fusion

Loop fusion

```
Example
for i=1 to N do
A[i] = B[i] + 1
endfor
for i=1 to N do
C[i] = A[i] / 2
endfor
for i=1 to N do
D[i] = 1 / C[i+1]
endfor
```



Before Loop Fusion

Limitations of Compiler Optimization

- Operate Under Fundamental Constraint
 - Must not cause any change in program behavior under any possible condition
 - Often prevents it from making optimizations when would only affect behavior under pathological conditions.
- Behavior that may be obvious to the programmer can be obfuscated by languages and coding styles
 - e.g., data ranges may be more limited than variable types suggest
- Most analysis is performed only within procedures
 - whole-program analysis is too expensive in most cases
- Most analysis is based only on static information
 - compiler has difficulty anticipating run-time inputs
- When in doubt, the compiler must be conservative